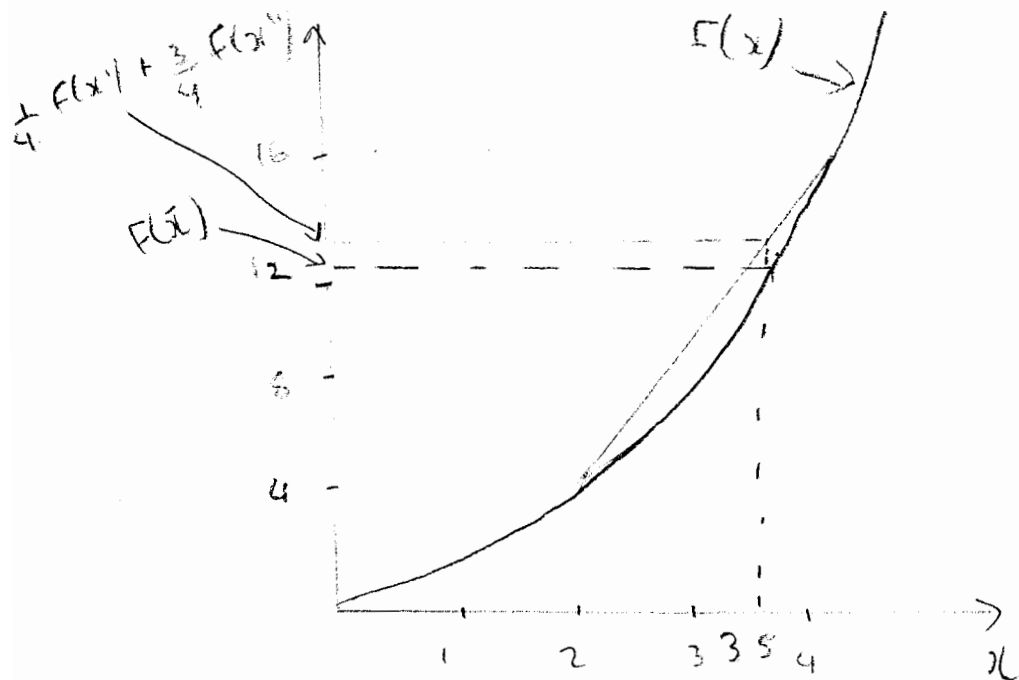


$$1. \quad x' = 2 \quad x'' = 4 \quad \lambda = \frac{1}{4} \quad y = x^2$$

$$\Rightarrow \bar{x} = \frac{1}{4} \cdot 2 + \frac{3}{4} \cdot 4 = 3.5$$

$$f(\bar{x}) = 3.5^2 = 12.25$$

$f(x)$ is s. convex if $f(\bar{x}) < \lambda f(x') + (1-\lambda)f(x'')$



$$= \frac{1}{4} \cdot 4 + \frac{3}{4} \cdot 16$$

$$= 13 \quad \checkmark$$

True $\forall x', x'' \quad \bar{x} = \lambda x' + (1-\lambda)x''$

$$\text{LHS } f(\bar{x}) = (\lambda x' + (1-\lambda)x'')^2 \\ = \lambda^2 x'^2 + 2\lambda(1-\lambda)x'x'' + (1-\lambda)^2 x''^2$$

$$< \text{RHS} = \lambda x'^2 + (1-\lambda)x''^2$$

$$\Rightarrow \text{need } (\lambda^2 - \lambda)x'^2 + \left(\frac{(1-\lambda)^2}{\lambda} - (1-\lambda) \right)x''^2 + 2\lambda(1-\lambda)x'x'' < 0$$

$$\Rightarrow (\lambda^2 - \lambda) [x'^2 + x''^2 - 2x'x''] < 0$$

$$\Rightarrow \lambda(1-\lambda) (x' - x'')^2 < 0$$

+ -
 always > 0 \checkmark

$$2. \quad y = e^{x^2}$$

$$f(x) \approx f(0) + x f'(0) + \frac{x^2}{2!} f''(0)$$

$$f(0) = e^{0^2} = 1$$

$$f'(x) = 2x e^{x^2} \Rightarrow f'(0) = 0$$

$$f''(x) = 2e^{x^2} + 4x^2 e^{x^2} \Rightarrow f''(0) = 2$$

$$\Rightarrow e^{x^2} \approx 1 + x \times 0 + \frac{x^2}{2!} \times 2 = 1 + x^2$$

$$\text{eg } x = 0.05 \Rightarrow e^{x^2} \approx 1 + 0.05^2 = 1.0025$$

$$\text{Actually } e^{0.05^2} = 1.002503$$

$$\therefore \text{error} = 0.000003$$

$$3. \quad x_1 = 20L_1^{\frac{1}{2}} \quad L_1 + L_2 = 100$$

$$x_2 = L_2$$

$$a. \quad MPL_1 = \frac{dx_1}{dL_1} = 10L_1^{-\frac{1}{2}}$$

$$MPL_2 = \frac{dx_2}{dL_2} = 1$$

$$b. \quad L_2 = x_2 \quad L_1 = \left(\frac{x_1}{20}\right)^2 = \frac{1}{400} x_1^2$$

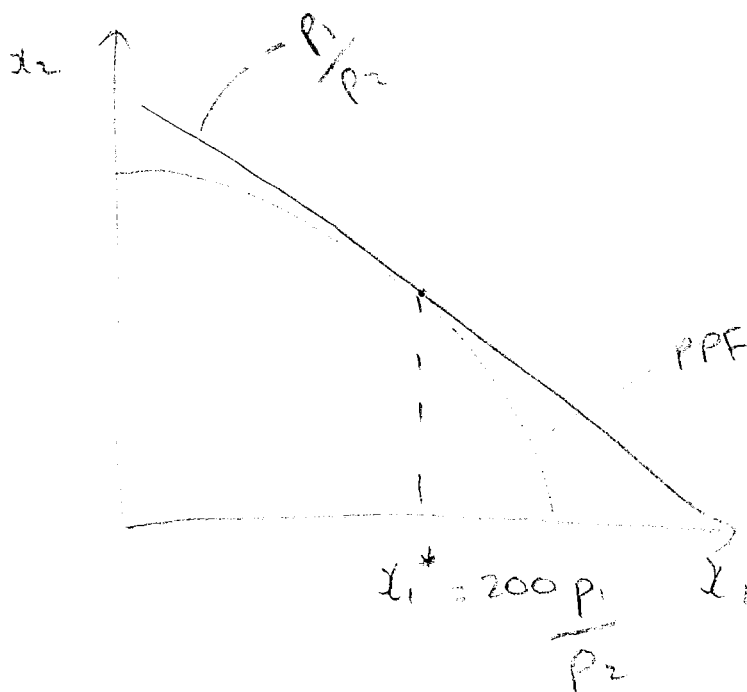
$$c. \quad \text{Use b.} \Rightarrow L_1 + L_2 = 100 = x_2 + \frac{1}{400} x_1^2$$

$$\Rightarrow x_2 = 100 - \frac{1}{400} x_1^2$$

$$\frac{dx_2}{dx_1} = -\frac{1}{200} x_1 < 0 \quad \forall x_1 > 0$$

$$\frac{d^2x_2}{dx_1^2} = -\frac{1}{200} < 0 \quad \forall x_1, x_2$$

\therefore PPF slopes \downarrow & is strictly concave



$$d. \quad \max y = p_1 x_1 + p_2 x_2$$

$$= p_1 x_1 + p_2 \left(100 - \frac{1}{400} x_1^2 \right)$$

$$\frac{dy}{dx_1} = p_1 - \frac{1}{200} p_2 x_1$$

$$= 0 \quad \text{when} \quad x_1^* = \frac{200 p_1}{p_2}$$

$$e. \quad \frac{dx_1^*}{dp_1} = \frac{200}{p_2} > 0 \quad \text{ie when } p_1 \uparrow, x_1 \uparrow$$

$$x_2^* = 100 - \frac{1}{400} (x_1^*)^2 = 100 - \frac{1}{400} \frac{40,000 p_1^2}{p_2^2}$$

$$= 100 - \frac{100 p_1^2}{p_2^2}$$

$$\frac{dx_2^*}{dp_1} = - \frac{200 p_1}{p_2^2} < 0$$

$$\text{ie } p_1 \uparrow \quad x_2 \downarrow$$

(see illustration)

Note = Comp Stats easy when explicit functions. As 4 about done it is general function form.

$$4. \quad \Pi = (p(x) - t)x - c(x)$$

$$a. \quad \frac{d\Pi}{dx} = \Pi'(x) = p'(x) \cdot x + (p(x) - t) - c'(x) = 0$$

$$\begin{aligned} \frac{d^2\Pi}{dx^2} &= p''(x) \cdot x + p'(x) + p'(x) - c''(x) \\ &= \underbrace{p''(x) \cdot x + 2p'(x)}_{-ve} - c''(x) \end{aligned}$$

$$< 0 \quad \forall x$$

\therefore SOSC is satisfied - global max.

b. Take TD of FOC (ie use imp. function rule)

or may use
3 step method
from lecture notes.

$$\Rightarrow p''(x)x \cdot dx + p'(x)dx + p'(x)dx - dt - c''(x)dx = 0$$

$$\Rightarrow (p''(x) \cdot x + 2p'(x) - c''(x))dx = dt$$

$$\Rightarrow \frac{dx}{dt} = \frac{1}{(-)} < 0 \text{ from SOSC}$$

\therefore As t falls, x will rise

$$\frac{dp}{dt} = \frac{dp}{dx} \cdot \frac{dx}{dt} = \frac{p'(x)}{(-)} > 0$$

\therefore As t falls, p will fall

$$5. \quad A\vec{x} = d \Rightarrow Q + bp^c = a$$

$$Q - bp^c = c$$

$$p^c - pp^c = t$$

$$\Rightarrow \begin{bmatrix} 1 & b & 0 \\ 1 & 0 & -e \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} Q \\ p^c \\ pp^c \end{bmatrix} = \begin{bmatrix} a \\ c \\ t \end{bmatrix}$$

$$\Rightarrow p^c = \frac{\begin{vmatrix} 1 & a & 0 \\ 1 & c & -e \\ 0 & t & -1 \end{vmatrix}}{|A|} = \frac{1(-c+et) - a(-1)}{1(0+e) - b(-1)} = \frac{a-c+et}{b+e}$$

$$6. \begin{bmatrix} 3 & 1 & 1 \\ 0 & 1 & -2 \\ 2 & -1 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 3 \end{bmatrix}$$

$$|A| = 3(4-2) - 1(0+4) + 1(0-2) = 0$$

\therefore not a unique solution

$$\therefore r(A) < 3 \quad \because |A| = 0$$

$$r(A) = 2 \quad \because \begin{vmatrix} 3 & 1 \\ 0 & 1 \end{vmatrix} \neq 0$$

$$B = \begin{bmatrix} 3 & 1 & 1 & 1 \\ 0 & 1 & -2 & 1 \\ 2 & -1 & 4 & 3 \end{bmatrix}$$

$$\begin{vmatrix} 3 & 1 & 1 \\ 0 & 1 & 1 \\ 2 & -1 & 3 \end{vmatrix} = 12 > 0 \quad \therefore r(B) = 3 > r(A),$$

so equations are inconsistent.

8.
$$U = [0.3x_1^{-3} + 0.7x_2^{-3}]^{-1/3}$$

$$dU = \frac{\partial U}{\partial x_1} dx_1 + \frac{\partial U}{\partial x_2} dx_2 = 0$$

$$\Rightarrow \frac{dx_2}{dx_1} = - \frac{\partial U / \partial x_1}{\partial U / \partial x_2}$$

$$= - \frac{[-\frac{1}{3}(\cdot)^{-4/3} \cdot -3 \times 0.3 x_1^{-4}]}{-\frac{1}{3}(\cdot)^{-4/3} \cdot -3 \times 0.7 x_2^{-4}}$$

$$= - \frac{0.3}{0.7} \cdot \frac{x_2^4}{x_1^4} \quad \text{or} \quad 0.43 \frac{x_2^4}{x_1^4}$$

7. $U(x, p) \quad p = g(x)$

$$\frac{dU}{dx} = \frac{\partial U}{\partial x} + \frac{\partial U}{\partial p} \frac{dp}{dx} \quad \text{or} \quad \frac{dU}{dx} = U_x + U_p \cdot g'(x)$$

The total derivative of U w.r.t x takes into account the partial effect of a change in x , U_x (holding p constant) AND the effect that p has on utility given that a change in x will trigger a change in p ($g'(x)$) which in turn changes U (U_p). Here the total derivative will be smaller than the partial because, while an increase in x causes U to rise, this is offset by the increase in p , which causes U to fall.